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Spivak's Calculus On Manifolds: Solutions Manual Thomas Hughes August 2017. Chapter 1 Functions on Euclidean Space 1.1 Prove that  $\sum_{i=1}^n x_i y_i = \sum_{i=1}^n x_i y_i$  Proof. If  $\{e_1, e_2, \dots, e_n\}$  is the usual basis on  $\mathbb{R}^n$ , then we can write  $x = x_1 e_1 + x_2 e_2 + \dots + x_n e_n$  and thus  $\sum_{i=1}^n x_i y_i = \sum_{i=1}^n x_i e_i \cdot \sum_{i=1}^n y_i e_i = \sum_{i=1}^n x_i y_i$  1.2 When does equality hold in Theorem 1-1(3)? Proof. Notice in the ...

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~~Solutions and Comments: Spivak's "Calculus on Manifolds"~~

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4 CHAPTER 1 FUNCTIONS ON EUCLIDEAN SPACE IExercise 8 (1-8). If  $x; y \in \mathbb{R}^n$  are non-zero, the angle between  $x$  and  $y$ , denoted  $\angle(x; y)$ , is defined as  $\arccos \frac{\langle x; y \rangle}{\|x\| \|y\|}$ , which makes sense by Theorem 1-1 (2). The linear transformation  $T$  is angle preserving if  $T$  is 1-1, and for  $x; y \neq 0$  we have  $\angle(Tx; Ty) = \angle(x; y)$ . a. Prove that if  $T$  is norm preserving, then  $T$  is angle preserving. b. If there is a basis.  $x$

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